Managing system resources on Red Hat Enterprise Linux 6

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A. Revision History
Preface

1. Document Conventions
This manual uses several conventions to highlight certain words and phrases and draw attention to specific pieces of information.

In PDF and paper editions, this manual uses typefaces drawn from the *Liberation Fonts*\(^1\) set. The Liberation Fonts set is also used in HTML editions if the set is installed on your system. If not, alternative but equivalent typefaces are displayed. Note: Red Hat Enterprise Linux 5 and later includes the Liberation Fonts set by default.

1.1. Typographic Conventions
Four typographic conventions are used to call attention to specific words and phrases. These conventions, and the circumstances they apply to, are as follows.

Mono-spaced Bold
Used to highlight system input, including shell commands, file names and paths. Also used to highlight keycaps and key combinations. For example:

To see the contents of the file *my_next_bestselling_novel* in your current working directory, enter the `cat my_next_bestselling_novel` command at the shell prompt and press *Enter* to execute the command.

The above includes a file name, a shell command and a keycap, all presented in mono-spaced bold and all distinguishable thanks to context.

Key combinations can be distinguished from keycaps by the hyphen connecting each part of a key combination. For example:

Press *Enter* to execute the command.

Press *Ctrl*+*Alt*+*F2* to switch to the first virtual terminal. Press *Ctrl*+*Alt*+*F1* to return to your X-Windows session.

The first paragraph highlights the particular keycap to press. The second highlights two key combinations (each a set of three keycaps with each set pressed simultaneously).

If source code is discussed, class names, methods, functions, variable names and returned values mentioned within a paragraph will be presented as above, in *mono-spaced bold*. For example:

File-related classes include *filesystem* for file systems, *file* for files, and *dir* for directories. Each class has its own associated set of permissions.

Proportional Bold
This denotes words or phrases encountered on a system, including application names; dialog box text; labeled buttons; check-box and radio button labels; menu titles and sub-menu titles. For example:

Choose *System* → *Preferences* → *Mouse* from the main menu bar to launch *Mouse Preferences*. In the *Buttons* tab, click the *Left-handed mouse* check box and click

\(^1\) [https://fedorahosted.org/liberation-fonts/](https://fedorahosted.org/liberation-fonts/)
Close to switch the primary mouse button from the left to the right (making the mouse suitable for use in the left hand).

To insert a special character into a gedit file, choose Applications → Accessories → Character Map from the main menu bar. Next, choose Search → Find… from the Character Map menu bar, type the name of the character in the Search field and click Next. The character you sought will be highlighted in the Character Table. Double-click this highlighted character to place it in the Text to copy field and then click the Copy button. Now switch back to your document and choose Edit → Paste from the gedit menu bar.

The above text includes application names; system-wide menu names and items; application-specific menu names; and buttons and text found within a GUI interface, all presented in proportional bold and all distinguishable by context.

**Mono-spaced Bold Italic** or **Proportional Bold Italic**

Whether mono-spaced bold or proportional bold, the addition of italics indicates replaceable or variable text. Italics denotes text you do not input literally or displayed text that changes depending on circumstance. For example:

To connect to a remote machine using ssh, type `ssh username@domain.name` at a shell prompt. If the remote machine is `example.com` and your username on that machine is john, type `ssh john@example.com`.

The `mount -o remount file-system` command remounts the named file system. For example, to remount the `/home` file system, the command is `mount -o remount /home`.

To see the version of a currently installed package, use the `rpm -q package` command. It will return a result as follows: `package-version-release`.

Note the words in bold italics above — username, domain.name, file-system, package, version and release. Each word is a placeholder, either for text you enter when issuing a command or for text displayed by the system.

Aside from standard usage for presenting the title of a work, italics denotes the first use of a new and important term. For example:

Publican is a DocBook publishing system.

## 1.2. Pull-quote Conventions

Terminal output and source code listings are set off visually from the surrounding text.

Output sent to a terminal is set in **mono-spaced roman** and presented thus:

```
books        Desktop   documentation  drafts  mss    photos   stuff  svn
books_tests  Desktop1  downloads      images  notes  scripts  svgs
```

Source-code listings are also set in **mono-spaced roman** but add syntax highlighting as follows:

```
package org.jboss.book.jca.ex1;

import javax.naming.InitialContext;
```
public class ExClient
{
    public static void main(String args[])
    throws Exception
    {
        InitialContext iniCtx = new InitialContext();
        Object ref = iniCtx.lookup("EchoBean");
        EchoHome home = (EchoHome) ref;
        Echo echo = home.create();

        System.out.println("Created Echo");

        System.out.println("Echo.echo('Hello') = " + echo.echo("Hello"));
    }
}

1.3. Notes and Warnings
Finally, we use three visual styles to draw attention to information that might otherwise be overlooked.

Note
Notes are tips, shortcuts or alternative approaches to the task at hand. Ignoring a note should have no negative consequences, but you might miss out on a trick that makes your life easier.

Important
Important boxes detail things that are easily missed: configuration changes that only apply to the current session, or services that need restarting before an update will apply. Ignoring a box labeled 'Important' will not cause data loss but may cause irritation and frustration.

Warning
Warnings should not be ignored. Ignoring warnings will most likely cause data loss.

2. Getting Help and Giving Feedback

2.1. Do You Need Help?
If you experience difficulty with a procedure described in this documentation, visit the Red Hat Customer Portal at http://access.redhat.com. Through the customer portal, you can:

• search or browse through a knowledgebase of technical support articles about Red Hat products.

• submit a support case to Red Hat Global Support Services (GSS).
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- access other product documentation.

Red Hat also hosts a large number of electronic mailing lists for discussion of Red Hat software and technology. You can find a list of publicly available mailing lists at https://www.redhat.com/mailman/listinfo. Click on the name of any mailing list to subscribe to that list or to access the list archives.

2.2. We Need Feedback!

If you find a typographical error in this manual, or if you have thought of a way to make this manual better, we would love to hear from you! Please submit a report in Bugzilla: http://bugzilla.redhat.com against the product Red Hat Enterprise Linux 6.

When submitting a bug report, be sure to mention the manual’s identifier: doc-Resource_Management_Guide

If you have a suggestion for improving the documentation, try to be as specific as possible when describing it. If you have found an error, please include the section number and some of the surrounding text so we can find it easily.
Introduction to Control Groups (Cgroups)

Red Hat Enterprise Linux 6 provides a new kernel feature: control groups, which are called by their shorter name cgroups in this guide. Cgroups allow you to allocate resources—such as CPU time, system memory, network bandwidth, or combinations of these resources—among user-defined groups of tasks (processes) running on a system. You can monitor the cgroups you configure, deny cgroups access to certain resources, and even reconfigure your cgroups dynamically on a running system. The cgconfig (control group config) service can be configured to start up at boot time and reestablish your predefined cgroups, thus making them persistent across reboots.

By using cgroups, system administrators gain fine-grained control over allocating, prioritizing, denying, managing, and monitoring system resources. Hardware resources can be smartly divided up among tasks and users, increasing overall efficiency.

1.1. How Control Groups Are Organized

Cgroups are organized hierarchically, like processes, and child cgroups inherit some of the attributes of their parents. However, there are differences between the two models.

The Linux Process Model

All processes on a Linux system are child processes of a common parent: the init process, which is executed by the kernel at boot time and starts other processes (which may in turn start child processes of their own). Because all processes descend from a single parent, the Linux process model is a single hierarchy, or tree.

Additionally, every Linux process except init inherits the environment (such as the PATH variable) and certain other attributes (such as open file descriptors) of its parent process.

The Cgroup Model

Cgroups are similar to processes in that:

• they are hierarchical, and

• child cgroups inherit certain attributes from their parent cgroup.

The fundamental difference is that many different hierarchies of cgroups can exist simultaneously on a system. If the Linux process model is a single tree of processes, then the cgroup model is one or more separate, unconnected trees of tasks (i.e. processes).

Multiple separate hierarchies of cgroups are necessary because each hierarchy is attached to one or more subsystems. A subsystem represents a single resource, such as CPU time or memory. Red Hat Enterprise Linux 6 provides nine cgroup subsystems, listed below by name and function.

Available Subsystems in Red Hat Enterprise Linux

• blkio — this subsystem sets limits on input/output access to and from block devices such as physical drives (disk, solid state, USB, etc.).

1 The parent process is able to alter the environment before passing it to a child process.

2 You should be aware that subsystems are also called resource controllers, or simply controllers, in the libcgroup man pages and other documentation.
• cpu — this subsystem uses the scheduler to provide cgroup tasks access to the CPU.

• cpuacct — this subsystem generates automatic reports on CPU resources used by tasks in a cgroup.

• cpuset — this subsystem assigns individual CPUs (on a multicore system) and memory nodes to tasks in a cgroup.

• devices — this subsystem allows or denies access to devices by tasks in a cgroup.

• freezer — this subsystem suspends or resumes tasks in a cgroup.

• memory — this subsystem sets limits on memory use by tasks in a cgroup, and generates automatic reports on memory resources used by those tasks.

• net_cls — this subsystem tags network packets with a class identifier (classid) that allows the Linux traffic controller (tc) to identify packets originating from a particular cgroup task.

• ns — the namespace subsystem.

Subsystems are also known as resource controllers

You may come across the term resource controller or simply controller in cgroup literature such as the man pages or kernel documentation. Both of these terms are synonymous with "subsystem", and arise from the fact that a subsystem typically schedules a resource or applies a limit to the cgroups in the hierarchy it is attached to.

The definition of a subsystem (resource controller) is quite general: it is something that acts upon a group of tasks, i.e. processes.

1.2. Relationships Between Subsystems, Hierarchies, Control Groups and Tasks

Remember that system processes are called tasks in cgroup terminology.

Here are a few simple rules governing the relationships between subsystems, hierarchies of cgroups, and tasks, along with explanatory consequences of those rules.

**Rule 1**

A single hierarchy can have one or more subsystems attached to it.

As a consequence, the cpu and memory subsystems (or any number of subsystems) can be attached to a single hierarchy, as long as each one is not attached to any other hierarchy which has any other subsystems attached to it already (see Rule 2).
Rule 2

Any single subsystem (such as `cpu`) cannot be attached to more than one hierarchy if one of those hierarchies has a different subsystem attached to it already.

As a consequence, the `cpu` subsystem can never be attached to two different hierarchies if one of those hierarchies already has the `memory` subsystem attached to it. However, a single subsystem can be attached to two hierarchies if both of those hierarchies have only that subsystem attached.
create, each task on the system can be a member of exactly one cgroup in that hierarchy. A single task may be in multiple cgrouns, as long as each of those cgrouns is in a different hierarchy. As soon as a task becomes a member of a second cgroup in the same hierarchy, it is removed from the first cgroup in that hierarchy. At no time is a task ever in two different cgrouns in the same hierarchy.

As a consequence, if the cpu and memory subsystems are attached to a hierarchy named cpu_mem_cg, and the net_cls subsystem is attached to a hierarchy named net, then a running httpd process could be a member of any one cgroup in cpu_and_mem, and any one cgroup in net.

The cgroup in cpu_mem_cg that the httpd process is a member of might restrict its CPU time to half of that allotted to other processes, and limit its memory usage to a maximum of 1024 MB. Additionally, the cgroup in net that it is a member of might limit its transmission rate to 30 megabytes per second.

When the first hierarchy is created, every task on the system is a member of at least one cgroup: the root cgroup. When using cgrouns, therefore, every system task is always in at least one cgroup.

![Diagram]

**Rule 3**

Any process (task) on the system which forks itself creates a child process (task). A child task automatically inherits the cgroup membership of its parent but can be moved to different cgrouns as needed. Once forked, the parent and child processes are completely independent.

As a consequence, consider the httpd task that is a member of the cgroup named half_cpu_1gb_max in the cpu_and_mem hierarchy, and a member of the cgroup trans_rate_30 in the net hierarchy. When that httpd process forks itself, its child process automatically becomes a member of the half_cpu_1gb_max cgroup, and the trans_rate_30 cgroup. It inherits the exact same cgrouns its parent task belongs to.

From that point forward, the parent and child tasks are completely independent of each other: changing the cgrouns that one task belongs to does not affect the other. Neither will changing cgrouns of a parent task affect any of its grandchildren in any way. To summarize: any child task always initially inherit memberships to the exact same cgrouns as their parent task, but those memberships can be changed or removed later.
1.3. Implications for Resource Management

- Because a task can belong to only a single cgroup in any one hierarchy, there is only one way that a task can be limited or affected by any single subsystem. This is logical: a feature, not a limitation.

- You can group several subsystems together so that they affect all tasks in a single hierarchy. Because cgroups in that hierarchy have different parameters set, those tasks will be affected differently.

- It may sometimes be necessary to refactor a hierarchy. An example would be removing a subsystem from a hierarchy that has several subsystems attached, and attaching it to a new, separate hierarchy.

- Conversely, if the need for splitting subsystems among separate hierarchies is reduced, you can remove a hierarchy and attach its subsystems to an existing one.

- The design allows for simple cgroup usage, such as setting a few parameters for specific tasks in a single hierarchy, such as one with just the cpu and memory subsystems attached.

- The design also allows for highly specific configuration: each task (process) on a system could be a member of each hierarchy, each of which has a single attached subsystem. Such a configuration would give the system administrator absolute control over all parameters for every single task.
Using Control Groups

The easiest way to work with cgroups is to install the libcgroup package, which contains a number of cgroup-related command line utilities and their associated man pages. It is possible to mount hierarchies and set cgroup parameters (non-persistently) using shell commands and utilities available on any system. However, using the libcgroup-provided utilities simplifies the process and extends your capabilities. Therefore, this guide focuses on libcgroup commands throughout. In most cases, we have included the equivalent shell commands to help describe the underlying mechanism. However, we recommend that you use the libcgroup commands wherever practical.

Installing the libcgroup package

In order to use cgroups, first ensure the libcgroup package is installed on your system by running, as root:

```
-]# yum install libcgroup
```

2.1. The cgconfig Service

The cgconfig service installed with the libcgroup package provides a convenient way to create hierarchies, attach subsystems to hierarchies, and manage cgroups within those hierarchies. We recommend that you use cgconfig to manage hierarchies and cgroups on your system.

The cgconfig service is not started by default on Red Hat Enterprise Linux 6. When you start the service with chkconfig, it reads the cgroup configuration file — /etc/cgconfig.conf. Cgroups are therefore recreated from session to session and become persistent. Depending on the contents of the configuration file, cgconfig can create hierarchies, mount necessary file systems, create cgroups, and set subsystem parameters for each group.

The default /etc/cgconfig.conf file installed with the libcgroup package creates and mounts an individual hierarchy for each subsystem, and attaches the subsystems to these hierarchies.

If you stop the cgconfig service (with the service cgconfig stop command), it unmounts all the hierarchies that it mounted.

2.1.1. The /etc/cgconfig.conf File

The /etc/cgconfig.conf file contains two major types of entry — mount and group. Mount entries create and mount hierarchies as virtual file systems, and attach subsystems to those hierarchies. Mount entries are defined using the following syntax:

```
mount {
  <controller> = <path>;
  ...
}
```

See Example 2.1, “Creating a mount entry” for an example usage.

Example 2.1. Creating a mount entry

The following example creates a hierarchy for the cpuset subsystem:
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```
mount {
    cpuset = /cgroup/red;
}
```

the equivalent of the shell commands:

```
~]# mkdir /cgroup/red
~]# mount -t cgroup -o cpuset red /cgroup/red
```

Group entries create cgroups and set subsystem parameters. Group entries are defined using the following syntax:

```
group <name> {
    [ <permissions> ]
    <controller> {
        <param name> = <param value>;
        ...
    }
    ...
}
```

Note that the `permissions` section is optional. To define permissions for a group entry, use the following syntax:

```
perm {
    task {
        uid = <task user>;
        gid = <task group>;
    }
    admin {
        uid = <admin name>;
        gid = <admin group>;
    }
}
```

See Example 2.2, “Creating a group entry” for example usage:

**Example 2.2. Creating a group entry**

The following example creates a cgroup for SQL daemons, with permissions for users in the `sqladmin` group to add tasks to the cgroup and the `root` user to modify subsystem parameters:

```
group daemons/sql {
    perm {
        task {
            uid = root;
            gid = sqladmin;
        }
        admin {
            uid = root;
            gid = root;
        }
        cpu {
            cpu.shares = 100;
        }
    }
}
```
When combined with the example of the mount entry in *Example 2.1, “Creating a mount entry”*, the equivalent shell commands are:

```bash
[~]# mkdir -p /cgroup/cpu/daemons/sql
[~]# chown root:root /cgroup/cpu/daemons/sql/*
[~]# chown root:sqladmin /cgroup/cpu/daemons/sql/tasks
[~]# echo 100 > /cgroup/cpu/daemons/sql/cpu.shares
```

**Restart the cgconfig service for the changes to take effect**

You must restart the cgconfig service for the changes in the `/etc/cgconfig.conf` to take effect:

```bash
[~]# service cgconfig restart
```

When you install the *libcgroup* package, a sample configuration file is written to `/etc/cgconfig.conf`. The hash symbols (`#`) at the start of each line comment that line out and make it invisible to the cgconfig service.

### 2.2. Creating a Hierarchy and Attaching Subsystems

**Effects on running systems**

The following instructions, which cover creating a new hierarchy and attaching subsystems to it, assume that cggroups are not already configured on your system. In this case, these instructions will not affect the operation of the system. Changing the tunable parameters in a cgroup with tasks, however, may immediately affect those tasks. This guide alerts you the first time it illustrates changing a tunable cgroup parameter that may affect one or more tasks.

On a system on which cggroups are already configured (either manually, or by the cgconfig service) these commands will fail unless you first unmount existing hierarchies, which will affect the operation of the system. Do not experiment with these instructions on production systems.

To create a hierarchy and attach subsystems to it, edit the `mount` section of the `/etc/cgconfig.conf` file as root. Entries in the `mount` section have the following format:

```
subsystem = /group/hierarchy;
```

When cgconfig next starts, it will create the hierarchy and attach the subsystems to it.

The following example creates a hierarchy called `cpu_and_mem` and attaches the `cpu`, `cpuset`, `cpuacct`, and `memory` subsystems to it.

```
mount {
```
Alternative method
You can also use shell commands and utilities to create hierarchies and attach subsystems to them.

Create a *mount point* for the hierarchy as root. Include the name of the cgroup in the mount point:

```bash
~$ mkdir /cgroup/name
```

For example:

```bash
~$ mkdir /cgroup/cpu_and_mem
```

Next, use the `mount` command to mount the hierarchy and simultaneously attach one or more subsystems. For example:

```bash
~$ mount -t cgroup -o subsystems name /cgroup/name
```

Where *subsystems* is a comma-separated list of subsystems and *name* is the name of the hierarchy. Brief descriptions of all available subsystems are listed in *Available Subsystems in Red Hat Enterprise Linux*, and *Chapter 3, Subsystems and Tunable Parameters* provides a detailed reference.

**Example 2.3. Using the mount command to attach subsystems**
In this example, a directory named `/cgroup/cpu_and_mem` already exists, which will serve as the mount point for the hierarchy that we create. We will attach the cpu, cpuset and memory subsystems to a hierarchy we name `cpu_and_mem`, and mount the `cpu_and_mem` hierarchy on `/cgroup/cpu_and_mem`:

```bash
~$ mount -t cgroup -o cpu,cpuset,memory cpu_and_mem /cgroup/cpu_and_mem
```

You can list all available subsystems along with their current mount points (i.e. where the hierarchy they are attached to is mounted) with the `lssubsys` command:

```bash
~$ lssubsys -am
```

This output indicates that:

- the cpu, cpuset and memory subsystems are attached to a hierarchy mounted on `/cgroup/cpu_and_mem`, and

---

1 The `lssubsys` command is one of the utilities provided by the `libcgroup` package. You must install `libcgroup` to use it: refer to *Chapter 2, Using Control Groups* if you are unable to run `lssubsys`. 
• the net_cls, ns, cpacct, devices, freezer and blkio subsystems are as yet unattached to any hierarchy, as illustrated by the lack of a corresponding mount point.

2.3. Attaching Subsystems to, and Detaching Them From, an Existing Hierarchy

To add a subsystem to an existing hierarchy, detach it from an existing hierarchy, or move it to a different hierarchy, edit the `mount` section of the `/etc/cgconfig.conf` file as root, using the same syntax described in Section 2.2, “Creating a Hierarchy and Attaching Subsystems”. When cgconfig next starts, it will reorganize the subsystems according to the hierarchies that you specify.

Alternative method

To add an unattached subsystem to an existing hierarchy, remount the hierarchy. Include the extra subsystem in the `mount` command, together with the `remount` option.

Example 2.4. Remounting a hierarchy to add a subsystem

The `lssubsys` command shows cpu, cpuset, and memory subsystems attached to the cpu_and_mem hierarchy:

```
~]# lssubsys -am
cpu,cpuset,memory /cgroup/cpu_and_mem
net_cls
ns
cpacct
devices
freezer
blkio
```

We remount the cpu_and_mem hierarchy, using the `remount` option, and including cpacct in the list of subsystems:

```
~]# mount -t cgroup -o remount,cpu,cpuset,cpuacct,memory cpu_and_mem /cgroup/cpu_and_mem
```

The `lssubsys` command now shows cpacct attached to the cpu_and_mem hierarchy:

```
~]# lssubsys -am
cpu,cpuacct,cpuset,memory /cgroup/cpu_and_mem
net_cls	ns
devices
freezer
blkio
```

Analogously, you can detach a subsystem from an existing hierarchy by remounting the hierarchy and omitting the subsystem name from the `-o` options. For example, to then detach the cpacct subsystem, simply remount and omit it:

```
~]# mount -t cgroup -o remount,cpu,cpuset,cpuacct,memory cpu_and_mem /cgroup/cpu_and_mem
```

2.4. Unmounting a Hierarchy

You can `umount` a hierarchy of cgroups with the `umount` command:
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~]\# umount /cgroup/name

For example:

~]\# umount /cgroup/cpu_and_mem

If the hierarchy is currently empty (that is, it contains only the root cgroup) the hierarchy is deactivated when it is unmounted. If the hierarchy contains any other cgroups, the hierarchy remains active in the kernel even though it is no longer mounted.

To remove a hierarchy, ensure that all child cgroups are removed before you unmount the hierarchy, or use the cgclear command which can deactivate a hierarchy even when it is not empty — refer to Section 2.12, “Unloading Control Groups”.

2.5. Creating Control Groups

Use the cgcreate command to create cgroups. The syntax for cgcreate is:

cgcreate -t uid:gid -a uid:gid -g subsystems:path

where:

- -t (optional) — specifies a user (by user ID, uid) and a group (by group ID, gid) to own the tasks pseudo-file for this cgroup. This user can add tasks to the cgroup.

  Removing tasks

  Note that the only way to remove a task from a cgroup is to move it to a different cgroup. To move a task, the user must have write access to the destination cgroup; write access to the source cgroup is unimportant.

- -a (optional) — specifies a user (by user ID, uid) and a group (by group ID, gid) to own all pseudo-files other than tasks for this cgroup. This user can modify the access that the tasks in this cgroup have to system resources.

- -g — specifies the hierarchy in which the cgroup should be created, as a comma-separated list of the subsystems associated with those hierarchies. If the subsystems in this list are in different hierarchies, the group is created in each of these hierarchies. The list of hierarchies is followed by a colon and the path to the child group relative to the hierarchy. Do not include the hierarchy mount point in the path.

  For example, the cgroup located in the directory /cgroup/cpu_and_mem/lab1/ is called just lab1 — its path is already uniquely determined because there is at most one hierarchy for a given subsystem. Note also that the group is controlled by all the subsystems that exist in the hierarchies in which the cgroup is created, even though these subsystems have not been specified in the cgcreate command — refer to Example 2.5, “cgcreate usage”.

Because all cgroups in the same hierarchy have the same controllers, the child group has the same controllers as its parent.
Example 2.5. cgcreate usage
Consider a system where the cpu and memory subsystems are mounted together in the cpu_and_mem hierarchy, and the net_cls controller is mounted in a separate hierarchy called net. We now run:

```bash
~]# cgcreate -g cpu,net_cls:/test-subgroup
```

The `cgcreate` command creates two groups named test-subgroup, one in the cpu_and_mem hierarchy and one in the net hierarchy. The test-subgroup group in the cpu_and_mem hierarchy is controlled by the memory subsystem, even though we did not specify it in the cgcreate command.

Alternative method
To create a child of the cgroup directly, use the `mkdir` command:

```bash
~]# mkdir /cgroup/hierarchy/name/child_name
```

For example:

```bash
~]# mkdir /cgroup/cpuset/lab1/group1
```

2.6. Removing Control Groups
Remove cgroups with the cgdelete, which has a syntax similar to that of cgcreate. Run the following command:

```bash
cgdelete subsystems:path
```

where:

- `subsystems` is a comma-separated list of subsystems.
- `path` is the path to the cgroup relative to the root of the hierarchy.

For example:

```bash
~]# cgdelete cpu,net_cls:/test-subgroup
```

`cgdelete` can also recursively remove all subgroups with the option `-r`.

When you delete a cgroup, all its tasks move to its parent group.

2.7. Setting Parameters
Set subsystem parameters by running the `cgset` command from a user account with permission to modify the relevant cgroup. For example, if `/cgroup/cpuset/group1` exists, specify the CPUs to which this group has access with the following command:

```bash
cpuset]# cgset -r cpuset.cpus=0-1 group1
```

The syntax for `cgset` is:
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```
cgset -r parameter=value path_to_cgroup
```

where:

- `parameter` is the parameter to be set, which corresponds to the file in the directory of the given cgroup
- `value` is the value for the parameter
- `path_to_cgroup` is the path to the cgroup relative to the root of the hierarchy. For example, to set the parameter of the root group (if `/cgroup/cpuacct/` exists), run:

```
cpuacct]# cgset -r cpuacct.usage=0 /
```

Alternatively, because . is relative to the root group (that is, the root group itself) you could also run:

```
cpuacct]# cgset -r cpuacct.usage=0 .
```

Note, however, that / is the preferred syntax.

---

### Setting parameters for the root group

Only a small number of parameters can be set for the root group (such as the `cpuacct.usage` parameter shown in the examples above). This is because a root group owns all of the existing resources, therefore, it would make no sense to limit all existing processes by defining certain parameters, for example the `cpuset.cpu` parameter.

To set the parameter of `group1`, which is a subgroup of the root group, run:

```
cpuacct]# cgset -r cpuacct.usage=0 group1
```

A trailing slash on the name of the group (for example, `cpuacct.usage=0 group1/`) is optional.

The values that you can set with `cgset` might depend on values set higher in a particular hierarchy. For example, if `group1` is limited to use only CPU 0 on a system, you cannot set `group1/subgroup1` to use CPUs 0 and 1, or to use only CPU 1.

You can also use `cgset` to copy the parameters of one cgroup into another, existing cgroup. For example:

```
~]# cgset --copy-from group1/ group2/
```

The syntax to copy parameters with `cgset` is:

```
cgset --copy-from path_to_source_cgroup path_to_target_cgroup
```

where:

- `path_to_source_cgroup` is the path to the cgroup whose parameters are to be copied, relative to the root group of the hierarchy
Alternative method

path_to_target_cgroup is the path to the destination cgroup, relative to the root group of the hierarchy.

Ensure that any mandatory parameters for the various subsystems are set before you copy parameters from one group to another, or the command will fail. For more information on mandatory parameters, refer to Mandatory parameters.

Alternative method

To set parameters in a cgroup directly, insert values into the relevant subsystem pseudo-file using the **echo** command. For example, this command inserts the value **0-1** into the **cpuset.cpus** pseudo-file of the cgroup **group1**:

```
~
-# echo 0-1 > /cgroup/cpuset/group1/cpuset.cpus
```

With this value in place, the tasks in this cgroup are restricted to CPUs 0 and 1 on the system.

2.8. Moving a Process to a Control Group

Move a process into a cgroup by running the **cgclassify** command:

```
~
-# cgclassify -g cpu,memory:group1 1701
```

The syntax for **cgclassify** is:

```
cgclassify -g subsystems:path_to_cgroup pidlist
```

where:

- **subsystems** is a comma-separated list of subsystems, or * to launch the process in the hierarchies associated with all available subsystems. Note that if cgroups of the same name exist in multiple hierarchies, the **-g** option moves the processes in each of those groups. Ensure that the cgroup exists within each of the hierarchies whose subsystems you specify here.

- **path_to_cgroup** is the path to the cgroup within its hierarchies

- **pidlist** is a space-separated list of **process identifier** (PIDs)

You can also add the **--sticky** option before the **pid** to keep any child processes in the same cgroup. If you do not set this option and the **cgred** daemon is running, child processes will be allocated to cgroups based on the settings found in **/etc/cgrules.conf**. The process itself, however, will remain in the cgroup in which you started it.

Using **cgclassify**, you can move several processes simultaneously. For example, this command moves the processes with PIDs **1701** and **1138** into cgroup **group1**:

```
-# cgclassify -g cpu,memory:group1 1701 1138
```

Note that the PIDs to be moved are separated by spaces and that the groups specified should be in different hierarchies.

Alternative method

To move a process into a cgroup directly, write its PID to the **tasks** file of the cgroup. For example, to move a process with the PID **1701** into a cgroup at **/cgroup/lab1/group1**:
2.8.1. The cgred Daemon

Cgred is a daemon that moves tasks into cgroups according to parameters set in the /etc/cgrules.conf file. Entries in the /etc/cgrules.conf file can take one of the two forms:

• user hierarchies control_group
• user:command hierarchies control_group

For example:

```
maria   devices  /usergroup/staff
```

This entry specifies that any processes that belong to the user named maria access the devices subsystem according to the parameters specified in the /usergroup/staff cgroup. To associate particular commands with particular cgroups, add the command parameter, as follows:

```
maria:ftp  devices  /usergroup/staff/ftp
```

The entry now specifies that when the user named maria uses the ftp command, the process is automatically moved to the /usergroup/staff/ftp cgroup in the hierarchy that contains the devices subsystem. Note, however, that the daemon moves the process to the cgroup only after the appropriate condition is fulfilled. Therefore, the ftp process might run for a short time in the wrong group. Furthermore, if the process quickly spawns children while in the wrong group, these children might not be moved.

Entries in the /etc/cgrules.conf file can include the following extra notation:

• @ — when prefixed to user, indicates a group instead of an individual user. For example, @admins are all users in the admins group.
• * — represents "all". For example, * in the subsystem field represents all subsystems.
• % — represents an item the same as the item in the line above. For example:

```
@adminstaff  devices  /admingroup
@labstaff  %  %
```
2.9. Starting a Process in a Control Group

Mandatory parameters

Some subsystems have mandatory parameters that must be set before you can move a task into a cgroup which uses any of those subsystems. For example, before you move a task into a cgroup which uses the cpuset subsystem, the `cpuset.cpu` and `cpuset.mems` parameters must be defined for that cgroup.

The examples in this section illustrate the correct syntax for the command, but only work on systems on which the relevant mandatory parameters have been set for any controllers used in the examples. If you have not already configured the relevant controllers, you cannot copy example commands directly from this section and expect them to work on your system.

Refer to Chapter 3, Subsystems and Tunable Parameters for a description of which parameters are mandatory for given subsystems.

Launch processes in a cgroup by running the `cgexec` command. For example, this command launches the lynx web browser within the group1 cgroup, subject to the limitations imposed on that group by the cpu subsystem:

```
[~]# cgexec -g cpu:group1 lynx http://www.redhat.com
```

The syntax for `cgexec` is:

```
cgexec -g subsystems:path_to_cgroup command arguments
```

where:

- `subsystems` is a comma-separated list of subsystems, or `*` to launch the process in the hierarchies associated with all available subsystems. Note that, as with cgset described in Section 2.7, “Setting Parameters”, if cgroups of the same name exist in multiple hierarchies, the `-g` option creates processes in each of those groups. Ensure that the cgroup exists within each of the hierarchies whose subsystems you specify here.

- `path_to_cgroup` is the path to the cgroup relative to the hierarchy.

- `command` is the command to run.

- `arguments` are any arguments for the command.

You can also add the `--sticky` option before the `command` to keep any child processes in the same cgroup. If you do not set this option and the cgred daemon is running, child processes will be allocated to cgroups based on the settings found in `/etc/cgrules.conf`. The process itself, however, will remain in the cgroup in which you started it.

Alternative method

When you start a new process, it inherits the group of its parent process. Therefore, an alternative method for starting a process in a particular cgroup is to move your shell process to that group (refer to Section 2.8, “Moving a Process to a Control Group”), and then launch the process from that shell. For example:
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```bash
~# echo $$ > /cgroup/lab1/group1/tasks
lynx
```

Note that after exiting `lynx`, your existing shell is still in the `group1` cgroup. Therefore, an even better way would be:

```bash
~# sh -c "echo $$ > /cgroup/lab1/group1/tasks && lynx"
```

2.9.1. Starting a Service in a Control Group

You can start certain services in a cgroup. Services that can be started in cgroups must:

- use a `/etc/sysconfig/servicename` file
- use the `daemon()` function from `/etc/init.d/functions` to start the service

To make an eligible service start in a cgroup, edit its file in the `/etc/sysconfig` directory to include an entry in the form `CGROUP_DAEMON="subsystem:control_group"` where `subsystem` is a subsystem associated with a particular hierarchy, and `control_group` is a cgroup in that hierarchy. For example:

```
CGROUP_DAEMON="cpuset:daemons/sql"
```

2.9.2. Process Behavior in the Root Control Group

Certain blkio and cpu configuration options affect processes (tasks) running in the root cgroup in a different way than those in a subgroup. Consider the following example:

1. Create two subgroups under one root group: `/rootgroup/red/` and `/rootgroup/blue/`
2. In each subgroup and in the root group, define the `cpu.shares` configuration option and set it to 1.

In the scenario configured above, one process placed in each group (that is, one task in `/rootgroup/tasks`, `/rootgroup/red/tasks` and `/rootgroup/blue/tasks`) ends up consuming 33.33% of the CPU:

```
/rootgroup/ process: 33.33%
/rootgroup/blue/ process: 33.33%
/rootgroup/red/ process: 33.33%
```

Any other processes placed in subgroups `blue` and `red` result in the 33.33% percent of the CPU assigned to that specific subgroup to be split among the multiple processes in that subgroup.

However, multiple processes placed in the root group cause the CPU resource to be split per process, rather than per group. For example, if `/rootgroup/` contains three processes, `/rootgroup/red/` contains one process and `/rootgroup/blue/` contains one process, and the `cpu.shares` option is set to 1 in all groups, the CPU resource is divided as follows:

```
/rootgroup/ processes: 20% + 20% + 20%
/rootgroup/blue/ process: 20%
/rootgroup/red/ process: 20%
```
Therefore, it is advisable to move all processes from the root group to a specific subgroup when using the blkio and cpu configuration options which divide an available resource based on a weight or a share (for example, \texttt{cpu.shares} or \texttt{blkio.weight}). To move all tasks from the root group into a specific subgroup, you can use the following command:

```
rootgroup]# for i in `cat tasks`; do echo $i > red/tasks; done
```

## 2.10. Generating the /etc/cgconfig.conf File

Configuration for the \texttt{/etc/cgconfig.conf} file can be generated from the current cgroup configuration using the \texttt{cgsnapshot} utility. This utility takes a snapshot of the current state of all subsystems and their cgroups and returns their configuration as it would appear in the \texttt{/etc/cgconfig.conf} file. Example 2.6, “Using the cgsnapshot utility” shows an example usage of the \texttt{cgsnapshot} utility.

### Example 2.6. Using the cgsnapshot utility

Assume we configured cgroups on our system using the following commands:

```bash
~]$ mkdir /cgroup/cpu
~]$ mount -t cgroup -o cpu cpu /cgroup/cpu
~]$ mkdir /cgroup/cpu/lab1
~]$ mkdir /cgroup/cpu/lab2
~]$ echo 2 > /cgroup/cpu/lab1/cpu.shares
~]$ echo 3 > /cgroup/cpu/lab2/cpu.shares
~]$ echo 5000000 > /cgroup/cpu/lab1/cpu.rt_period_us
~]$ echo 4000000 > /cgroup/cpu/lab1/cpu.rt_runtime_us
~]$ mkdir /cgroup/cpuacct
~]$ mount -t cgroup -o cpuacct cpuacct /cgroup/cpuacct
```

The above commands mounted two subsystems and created two cgroups, for the cpu subsystem, with specific values for some of their parameters. Executing the \texttt{cgsnapshot} command (with the \texttt{-s} option and an empty \texttt{/etc/cgsnapshot_blacklist.conf} file\footnote{The \texttt{cpu.shares} parameter is specified in the \texttt{/etc/cgsnapshot_blacklist.conf} file by default, which would cause it to be omitted in the generated output in Example 2.6, “Using the cgsnapshot utility”. Thus, for the purposes of the example, an empty \texttt{/etc/cgsnapshot_blacklist.conf} file is used.}) then produces the following output:

```
~]$ cgsnapshot -s
# Configuration file generated by cgsnapshot
mount {
    cpu = /cgroup/cpu;
    cpuacct = /cgroup/cpuacct;
}

group lab2 {
    cpu {
        cpu.rt_period_us="1000000";
        cpu.rt_runtime_us="0";
        cpu.shares="3";
    }
}
group lab1 {
    cpu {
```

\footnote{The \texttt{cpu.shares} parameter is specified in the \texttt{/etc/cgsnapshot_blacklist.conf} file by default, which would cause it to be omitted in the generated output in Example 2.6, “Using the cgsnapshot utility”. Thus, for the purposes of the example, an empty \texttt{/etc/cgsnapshot_blacklist.conf} file is used.}
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```c
cpu.rt_period_us="5000000";
cpu.rt_runtime_us="4000000";
cpu.shares="2";
}
}
```

The -s option used in the example above tells cgssnapshot to ignore all warnings in the output file caused by parameters not being defined in the blacklist or whitelist of the cgssnapshot utility. For more information on parameter blacklisting, refer to Section 2.10.1, “Blacklisting Parameters”. For more information on parameter whitelisting, refer to Section 2.10.2, “Whitelisting Parameters”.

When not specifying any options, the output generated by cgssnapshot is returned on the standard output. Use the -f to specify a file to which the output should be redirected. For example:

```
~]$ cgssnapshot -f ~/test/cgconfig_test.conf
```

**The -f option overwrites the specified file**

When using the -f option, note that it overwrites any content in the file you specify. Therefore, it is advisable not to direct the output straight to the /etc/cgconfig.conf file.

The cgssnapshot utility can also create configuration files per subsystem. By specifying the name of a subsystem, the output will consist of the corresponding configuration for that subsystem:

```
~]$ cgssnapshot cpuacct
# Configuration file generated by cgssnapshot
mount {
   cpuacct = /cgroup/cpuacct;
}
```

**2.10.1. Blacklisting Parameters**

The cgssnapshot utility allows parameter blacklisting. If a parameter is blacklisted, it does not appear in the output generated by cgssnapshot. By default, the /etc/cgssnapshot_blacklist.conf file is checked for blacklisted parameters. If a parameter is not present in the blacklist, the whitelist is checked. To specify a different blacklist, use the -b option. For example:

```
~]$ cgssnapshot -b ~/test/my_blacklist.conf
```

**2.10.2. Whitelisting Parameters**

The cgssnapshot utility also allows parameter whitelisting. If a parameter is whitelisted, it appears in the output generated by cgssnapshot. If a parameter is neither blacklisted or whitelisted, a warning appears informing of this:

```
~]$ cgssnapshot -f ~/test/cgconfig_test.conf
WARNING: variable cpu.rt_period_us is neither blacklisted nor whitelisted
WARNING: variable cpu.rt_runtime_us is neither blacklisted nor whitelisted
```
Obtaining Information About Control Groups

By default, there is no whitelist configuration file. To specify which file to use as a whitelist, use the -w option. For example:

```text
~]$ cgsnapshot -w ~/test/my_whitelist.conf
```

Specifying the -t option tells cgsnapshot to generate a configuration with parameters from the whitelist only.

### 2.11. Obtaining Information About Control Groups

#### 2.11.1. Finding a Process

To find the cgroup to which a process belongs, run:

```text
~]$ ps -O cgroup
```

Or, if you know the PID for the process, run:

```text
~]$ cat /proc/PID/cgroup
```

#### 2.11.2. Finding a Subsystem

To find the subsystems that are available in your kernel and how are they mounted together to hierarchies, run:

```text
~]$ cat /proc/cgroups
```

Or, to find the mount points of particular subsystems, run:

```text
~]$ lssubsys -m subsystems
```

where subsystems is a list of the subsystems in which you are interested. Note that the lssubsys -m command returns only the top-level mount point per each hierarchy.

#### 2.11.3. Finding Hierarchies

We recommend that you mount hierarchies under /cgroup. Assuming this is the case on your system, list or browse the contents of that directory to obtain a list of hierarchies. If tree is installed on your system, run it to obtain an overview of all hierarchies and the cgroups within them:

```text
~]$ tree /cgroup/
```

#### 2.11.4. Finding Control Groups

To list the cgroups on a system, run:

```text
~]$ lscgroup
```

You can restrict the output to a specific hierarchy by specifying a controller and path in the format controller:path. For example:

```text
~]$ lscgroup cpuset:adminusers
```
lists only subgroups of the `adminusers` cgroup in the hierarchy to which the `cpuset` subsystem is attached.

### 2.11.5. Displaying Parameters of Control Groups

To display the parameters of specific cgroups, run:

```
~]$ cgget -r parameter list_of_cgroups
```

where `parameter` is a pseudo-file that contains values for a subsystem, and `list_of_cgroups` is a list of cgroups separated with spaces. For example:

```
~]$ cgget -r cpuset.cpus -r memory.limit_in_bytes lab1 lab2
```

displays the values of `cpuset.cpus` and `memory.limit_in_bytes` for cgroups `lab1` and `lab2`.

If you do not know the names of the parameters themselves, use a command like:

```
~]$ cgget -g cpuset /
```

### 2.12. Unloading Control Groups

This command destroys all control groups

The `cgclear` command destroys all cgroups in all hierarchies. If you do not have these hierarchies stored in a configuration file, you will not be able to readily reconstruct them.

To clear an entire cgroup file system, use the `cgclear` command.

All tasks in the cgroup are reallocated to the root node of the hierarchies, all cgroups are removed, and the file system itself is unmounted from the system, thus destroying all previously mounted hierarchies. Finally, the directory where the cgroup file system was mounted is actually deleted.

Using the `mount` command to create cgroups (as opposed to creating them using the `cgconfig` service) results in the creation of an entry in the `/etc/mtab` file (the mounted file systems table). This change is also reflected into the `/proc/mounts` file. However, the unloading of cgroups with the `cgclear` command, along with other `cgconfig` commands, uses a direct kernel interface which does not reflect its changes into the `/etc/mtab` file and only writes the new information into the `/proc/mounts` file. Thus, after unloading cgroups with the `cgclear` command, the unmounted cgroups may still be visible in the `/etc/mtab` file, and, consequently, displayed when the `mount` command is executed. It is advisable to refer to the `/proc/mounts` file for an accurate listing of all mounted cgroups.
2.13. Additional Resources
The definitive documentation for cgroup commands are the manual pages provided with the libcgroup package. The section numbers are specified in the list of man pages below.

The libcgroup Man Pages
• man 1 cgclassify — the cgclassify command is used to move running tasks to one or more cgroups.

  man 1 cgclear — the cgclear command is used to delete all cgroups in a hierarchy.

  man 5 cgconfig.conf — cgroups are defined in the cgconfig.conf file.

  man 8 cgconfigparser — the cgconfigparser command parses the cgconfig.conf file and mounts hierarchies.

  man 1 cgcreate — the cgcreate command creates new cgroups in hierarchies.

  man 1 cgdelete — the cgdelete command removes specified cgroups.

  man 1 cgexec — the cgexec command runs tasks in specified cgroups.

  man 1 cgget — the cgget command displays cgroup parameters.

  man 1 cgsnapshot — the cgsnapshot command generates a configuration file from existing subsystems.

  man 5 cgred.conf — cgred.conf is the configuration file for the cgred service.

  man 5 cgrules.conf — cgrules.conf contains the rules used for determining when tasks belong to certain cgroups.

  man 8 cgrulesengd — the cgrulesengd service distributes tasks to cgroups.

  man 1 cgset — the cgset command sets parameters for a cgroup.

  man 1 lscgroup — the lscgroup command lists the cgroups in a hierarchy.

  man 1 lssubsys — the lssubsys command lists the hierarchies containing the specified subsystems.
Subsystems and Tunable Parameters

Subsystems are kernel modules that are aware of cgroups. Typically, they are resource controllers that allocate varying levels of system resources to different cgroups. However, subsystems could be programmed for any other interaction with the kernel where the need exists to treat different groups of processes differently. The application programming interface (API) to develop new subsystems is documented in `cgroups.txt` in the kernel documentation, installed on your system at `/usr/share/doc/kernel-doc-kernel-version/Documentation/cgroups/` (provided by the `kernel-doc` package). The latest version of the cgroups documentation is also available online at `http://www.kernel.org/doc/Documentation/cgroups/cgroups.txt`. Note, however, that the features in the latest documentation might not match those available in the kernel installed on your system.

State objects that contain the subsystem parameters for a cgroup are represented as pseudofiles within the cgroup virtual file system. These pseudofiles can be manipulated by shell commands or their equivalent system calls. For example, `cpuset.cpus` is a pseudo-file that specifies which CPUs a cgroup is permitted to access. If `/cgroup/cpuset/webserver` is a cgroup for the web server that runs on a system, and we run the following command:

```
~ # echo 0,2 > /cgroup/cpuset/webserver/cpuset.cpus
```

The value `0,2` is written to the `cpuset.cpus` pseudofile and therefore limits any tasks whose PIDs are listed in `/cgroup/cpuset/webserver/tasks` to use only CPU 0 and CPU 2 on the system.

3.1. blkio

The Block I/O (blkio) subsystem controls and monitors access to I/O on block devices by tasks in cgroups. Writing values to some of these pseudofiles limits access or bandwidth, and reading values from some of these pseudofiles provides information on I/O operations.

The blkio subsystem offers two policies for controlling access to I/O:

1. **Proportional weight division** — implemented in the Completely Fair Queuing I/O scheduler, this policy allows you to set weights to specific cgroups. This means that each cgroup has a set percentage (depending on the weight of the cgroup) of all I/O operations reserved. For more information, refer to Section 3.1.1, “Proportional Weight Division Configuration Options”

2. **I/O throttling (Upper limit)** — used to set an upper limit for the number of I/O operations performed by a specific device. This means that a device can have a limited rate of read or write operations. For more information, refer to Section 3.1.2, “I/O Throttling Configuration Options”

Buffered write operations

Currently, the Block I/O subsystem does not work for buffered write operations. It is primarily targeted at direct I/O, although it works for buffered read operations.

3.1.1. Proportional Weight Division Configuration Options

**blkio.weight**

specifies the relative proportion (weight) of block I/O access available by default to a cgroup, in the range `100` to `1000`. This value is overridden for specific devices by the `blkio.weight_device` parameter. For example, to assign a default weight of `500` to a cgroup for access to block devices, run:
echo 500 > blkio.weight

blkio.weight_device
specifies the relative proportion (weight) of I/O access on specific devices available to a cgroup, in the range 100 to 1000. The value of this parameter overrides the value of the blkio.weight parameter for the devices specified. Values take the format major:minor weight, where major and minor are device types and node numbers specified in Linux Allocated Devices, otherwise known as the Linux Devices List and available from http://www.kernel.org/doc/Documentation/devices.txt. For example, to assign a weight of 500 to a cgroup for access to /dev/sda, run:

echo 8:0 500 > blkio.weight_device

In the Linux Allocated Devices notation, 8:0 represents /dev/sda.

blkio.time
reports the time that a cgroup had I/O access to specific devices. Entries have three fields: major, minor, and time. Major and minor are device types and node numbers specified in Linux Allocated Devices, and time is the length of time in milliseconds (ms).

blkio.sectors
reports the number of sectors transferred to or from specific devices by a cgroup. Entries have three fields: major, minor, and sectors. Major and minor are device types and node numbers specified in Linux Allocated Devices, and sectors is the number of disk sectors.

blkio.io_serviced
reports the number of I/O operations performed on specific devices by a cgroup as seen by the CFQ scheduler. Entries have four fields: major, minor, operation, and number. Major and minor are device types and node numbers specified in Linux Allocated Devices, operation represents the type of operation (read, write, sync, or async) and number represents the number of operations.

blkio.io_service_bytes
reports the number of bytes transferred to or from specific devices by a cgroup as seen by the CFQ scheduler. Entries have four fields: major, minor, operation, and bytes. Major and minor are device types and node numbers specified in Linux Allocated Devices, operation represents the type of operation (read, write, sync, or async) and bytes is the number of bytes transferred.

blkio.io_service_time
reports the total time between request dispatch and request completion for I/O operations on specific devices by a cgroup as seen by the CFQ scheduler. Entries have four fields: major, minor, operation, and time. Major and minor are device types and node numbers specified in Linux Allocated Devices, operation represents the type of operation (read, write, sync, or async) and time is the length of time in nanoseconds (ns). The time is reported in nanoseconds rather than a larger unit so that this report is meaningful even for solid-state devices.

blkio.io_wait_time
reports the total time I/O operations on specific devices by a cgroup spent waiting for service in the scheduler queues. When you interpret this report, note:

• the time reported can be greater than the total time elapsed, because the time reported is the cumulative total of all I/O operations for the cgroup rather than the time that the cgroup itself spent waiting for I/O operations. To find the time that the group as a whole has spent waiting, use the blkio.group_wait_time parameter.
• if the device has a queue_depth > 1, the time reported only includes the time until the request is dispatched to the device, not any time spent waiting for service while the device re-orders requests.

Entries have four fields: major, minor, operation, and time. Major and minor are device types and node numbers specified in Linux Allocated Devices, operation represents the type of operation (read, write, sync, or async) and time is the length of time in nanoseconds (ns). The time is reported in nanoseconds rather than a larger unit so that this report is meaningful even for solid-state devices.

blkio.io_merged
reports the number of BIOS requests merged into requests for I/O operations by a cgroup. Entries have two fields: number and operation. Number is the number of requests, and operation represents the type of operation (read, write, sync, or async).

blkio.io_queued
reports the number of requests queued for I/O operations by a cgroup. Entries have two fields: number and operation. Number is the number of requests, and operation represents the type of operation (read, write, sync, or async).

blkio.avg_queue_size
reports the average queue size for I/O operations by a cgroup, over the entire length of time of the group’s existence. The queue size is sampled every time a queue for this cgroup gets a timeslice. Note that this report is available only if CONFIG_DEBUG_BLK_CGROUP=y is set on the system.

blkio.group_wait_time
reports the total time (in nanoseconds — ns) a cgroup spent waiting for a timeslice for one of its queues. The report is updated every time a queue for this cgroup gets a timeslice, so if you read this pseudofile while the cgroup is waiting for a timeslice, the report will not contain time spent waiting for the operation currently queued. Note that this report is available only if CONFIG_DEBUG_BLK_CGROUP=y is set on the system.

blkio.empty_time
reports the total time (in nanoseconds — ns) a cgroup spent without any pending requests. The report is updated every time a queue for this cgroup has a pending request, so if you read this pseudofile while the cgroup has no pending requests, the report will not contain time spent in the current empty state. Note that this report is available only if CONFIG_DEBUG_BLK_CGROUP=y is set on the system.

blkio.idle_time
reports the total time (in nanoseconds — ns) the scheduler spent idling for a cgroup in anticipation of a better request than those requests already in other queues or from other groups. The report is updated every time the group is no longer idling, so if you read this pseudofile while the cgroup is idling, the report will not contain time spent in the current idling state. Note that this report is available only if CONFIG_DEBUG_BLK_CGROUP=y is set on the system.

blkio.dequeue
reports the number of times requests for I/O operations by a cgroup were dequeued by specific devices. Entries have three fields: major, minor, and number. Major and minor are device types and node numbers specified in Linux Allocated Devices, and number is the number of requests the group was dequeued. Note that this report is available only if CONFIG_DEBUG_BLK_CGROUP=y is set on the system.
3.1.2. I/O Throttling Configuration Options

blkio.throttle.read_bps_device

specifies the upper limit on the number of read operations a device can perform. The rate of the read operations is specified in bytes per second. Entries have three fields: major, minor, and bytes_per_second. Major and minor are device types and node numbers specified in Linux Allocated Devices, and bytes_per_second is the upper limit rate at which read operations can be performed. For example, to allow the /dev/sda device to perform read operations at a maximum of 10 MBps, run:

```
~ # echo "8:0 10485760" > /cgroups/blkio/test/blkio.throttle.read_bps_device
```

blkio.throttle.read_iops_device

specifies the upper limit on the number of read operations a device can perform. The rate of the read operations is specified in operations per second. Entries have three fields: major, minor, and operations_per_second. Major and minor are device types and node numbers specified in Linux Allocated Devices, and operations_per_second is the upper limit rate at which read operations can be performed. For example, to allow the /dev/sda device to perform a maximum of 10 read operations per second, run:

```
~ # echo "8:0 10" > /cgroups/blkio/test/blkio.throttle.read_iops_device
```

blkio.throttle.write_bps_device

specifies the upper limit on the number of write operations a device can perform. The rate of the write operations is specified in bytes per second. Entries have three fields: major, minor, and bytes_per_second. Major and minor are device types and node numbers specified in Linux Allocated Devices, and bytes_per_second is the upper limit rate at which write operations can be performed. For example, to allow the /dev/sda device to perform write operations at a maximum of 10 MBps, run:

```
~ # echo "8:0 10485760" > /cgroups/blkio/test/blkio.throttle.write_bps_device
```

blkio.throttle.write_iops_device

specifies the upper limit on the number of write operations a device can perform. The rate of the write operations is specified in operations per second. Entries have three fields: major, minor, and operations_per_second. Major and minor are device types and node numbers specified in Linux Allocated Devices, and operations_per_second is the upper limit rate at which read operations can be performed. For example, to allow the /dev/sda device to perform a maximum of 10 write operations per second, run:

```
~ # echo "8:0 10" > /cgroups/blkio/test/blkio.throttle.write_iops_device
```

blkio.throttle.io_serviced

reports the number of I/O operations performed on specific devices by a cgroup as seen by the throttling policy. Entries have four fields: major, minor, operation, and number. Major and minor are device types and node numbers specified in Linux Allocated Devices, operation represents the type of operation (read, write, sync, or async) and number represents the number of operations.

blkio.throttle.io_service_bytes

reports the number of bytes transferred to or from specific devices by a cgroup. The only difference between blkio.io_service_bytes and blkio.throttle.io_service_bytes
is that the former is not updated when the CFQ scheduler is operating on a request queue. Entries have four fields: major, minor, operation, and bytes. Major and minor are device types and node numbers specified in Linux Allocated Devices, operation represents the type of operation (read, write, sync, or async) and bytes is the number of bytes transferred.

3.1.3. Common Configuration Option
The following configuration option may be used for either of the policies listed in Section 3.1, “blkio”.

blkio.reset_stats
resets the statistics recorded in the other pseudofiles. Write an integer to this file to reset the statistics for this cgroup.

3.1.4. Example Usage
Refer to Example 3.1, “blkio proportional weight division” for a simple test of running two dd threads in two different cgroups with various blkio.weight values.

Example 3.1. blkio proportional weight division
1. Mount the blkio subsystem:

```bash
~]# mount -t cgroup -o blkio blkio /cgroup/blkio/
```

2. Create two cgroups for the blkio subsystem:

```bash
~]# mkdir /cgroup/blkio/test1/
~]# mkdir /cgroup/blkio/test2/
```

3. Set various blkio weights in the previously-created cgroups:

```bash
~]# echo 1000 > /cgroup/blkio/test1/blkio.weight
~]# echo 500 > /cgroup/blkio/test2/blkio.weight
```

4. Create two large files:

```bash
~]# dd if=/dev/zero of=file_1 bs=1M count=4000
~]# dd if=/dev/zero of=file_2 bs=1M count=4000
```

The above commands create two files (file_1 and file_2) of size 4 GB.

5. For each of the test cgroups, execute a dd command (which reads the contents of a file and outputs it to the null device) on one of the large files:

```bash
~]# cgexec -g blkio:test1 time dd if=file_1 of=/dev/null
~]# cgexec -g blkio:test2 time dd if=file_2 of=/dev/null
```

Both commands will output their completion time once they have finished.

6. Simultaneously with the two running dd threads, you can monitor the performance in real time by using the iotop utility. To install the iotop utility, execute, as root, the yum install iotop
command. The following is an example of the output as seen in the `iotop` utility while running the previously-started `dd` threads:

<table>
<thead>
<tr>
<th>TIME</th>
<th>TID</th>
<th>PRIO</th>
<th>USER</th>
<th>DISK READ</th>
<th>DISK WRITE</th>
<th>SWAPIN</th>
<th>IO</th>
<th>COMMAND</th>
</tr>
</thead>
<tbody>
<tr>
<td>15:18:04</td>
<td>15071</td>
<td>be/4</td>
<td>root</td>
<td>27.64 M/s</td>
<td>0.00 B/s</td>
<td>0.00 %</td>
<td>92.30 %</td>
<td>dd if=file_2 of=/dev/null</td>
</tr>
<tr>
<td>15:18:04</td>
<td>15069</td>
<td>be/4</td>
<td>root</td>
<td>55.52 M/s</td>
<td>0.00 B/s</td>
<td>0.00 %</td>
<td>88.48 %</td>
<td>dd if=file_1 of=/dev/null</td>
</tr>
</tbody>
</table>

In order to get the most accurate result in `Example 3.1, "blkio proportional weight division"`, prior to the execution of the `dd` commands, flush all file system buffers and free pagecache, dentries and inodes using the following commands:

```bash
-]# sync
-]# echo 3 > /proc/sys/vm/drop_caches
```

Additionally, you can enable group isolation which provides stronger isolation between groups at the expense of throughput. When group isolation is disabled, fairness can be expected only for a sequential workload. By default, group isolation is enabled and fairness can be expected for random I/O workloads as well. To enable group isolation, use the following command:

```bash
-]# echo 1 > /sys/block/<disk_device>/queue/iosched/group_isolation
```

where `<disk_device>` stands for the name of the desired device, for example sda.

### 3.2. cpu

The cpu subsystem schedules CPU access to cgroups. Access to CPU resources can be scheduled according to the following parameters, each one in a separate pseudofile within the cgroup virtual file system:

- `cpu.shares`
  - contains an integer value that specifies a relative share of CPU time available to the tasks in a cgroup. For example, tasks in two cgroups that have `cpu.shares` set to 1 will receive equal CPU time, but tasks in a cgroup that has `cpu.shares` set to 2 receive twice the CPU time of tasks in a cgroup where `cpu.shares` is set to 1.

- `cpu.rt_runtime_us`
  - applicable to realtime scheduling tasks only, this parameter specifies a period of time in microseconds (µs, represented here as "us") for the longest continuous period in which the tasks in a cgroup have access to CPU resources. Establishing this limit prevents tasks in one cgroup from monopolizing CPU time. If the tasks in a cgroup should be able to access CPU resources for 4 seconds out of every 5 seconds, set `cpu.rt_runtime_us` to 4000000 and `cpu.rt_period_us` to 5000000.

- `cpu.rt_period_us`
  - applicable to realtime scheduling tasks only, this parameter specifies a period of time in microseconds (µs, represented here as "us") for how regularly a cgroup's access to CPU resource should be reallocated. If the tasks in a cgroup should be able to access CPU resources for 4 seconds out of every 5 seconds, set `cpu.rt_runtime_us` to 4000000 and `cpu.rt_period_us` to 5000000.
3.3. cpuacct

The CPU Accounting (cpuacct) subsystem generates automatic reports on CPU resources used by the tasks in a cgroup, including tasks in child groups. Three reports are available:

cpuacct.usage
  reports the total CPU time (in nanoseconds) consumed by all tasks in this cgroup (including tasks lower in the hierarchy).

**Resetting cpuacct.usage**

To reset the value in cpuacct.usage, execute the following command:

```
~]$ echo 0 > /cgroups/cpuacct/cpuacct.usage
```

The above command also resets values in cpuacct.usage_percpu.

cpuacct.stat
  reports the user and system CPU time consumed by all tasks in this cgroup (including tasks lower in the hierarchy) in the following way:
  
  - **user** — CPU time consumed by tasks in user mode.
  - **system** — CPU time consumed by tasks in system (kernel) mode.

  CPU time is reported in the units defined by the USER_HZ variable.

cpuacct.usage_percpu
  reports the CPU time (in nanoseconds) consumed on each CPU by all tasks in this cgroup (including tasks lower in the hierarchy).

3.4. cpuset

The cpuset subsystem assigns individual CPUs and memory nodes to cgroups. Each cpuset can be specified according to the following parameters, each one in a separate pseudofile within the cgroup virtual file system:

**Mandatory parameters**

Some subsystems have mandatory parameters that must be set before you can move a task into a cgroup which uses any of those subsystems. For example, before you move a task into a cgroup which uses the cpuset subsystem, the **cpuset.cpus** and **cpuset.mems** parameters must be defined for that cgroup.

**cpuset.cpus (mandatory)**

specifies the CPUs that tasks in this cgroup are permitted to access. This is a comma-separated list in ASCII format, with dashes (“-”) to represent ranges. For example,
Chapter 3. Subsystems and Tunable Parameters

represents CPUs 0, 1, 2, and 16.

cpuset.mems (mandatory)
specifies the memory nodes that tasks in this cgroup are permitted to access. This is a comma-separated list in ASCII format, with dashes ("-"), to represent ranges. For example,

represents memory nodes 0, 1, 2, and 16.

cpuset.memory_migrate
contains a flag (0 or 1) that specifies whether a page in memory should migrate to a new node if the values in `cpuset.mems` change. By default, memory migration is disabled (0) and pages stay on the node to which they were originally allocated, even if this node is no longer one of the nodes now specified in `cpuset.mems`. If enabled (1), the system will migrate pages to memory nodes within the new parameters specified by `cpuset.mems`, maintaining their relative placement if possible — for example, pages on the second node on the list originally specified by `cpuset.mems` will be allocated to the second node on the list now specified by `cpuset.mems`, if this place is available.

cpuset.cpu_exclusive
contains a flag (0 or 1) that specifies whether cpusets other than this one and its parents and children can share the CPUs specified for this cpuset. By default (0), CPUs are not allocated exclusively to one cpuset.

cpuset.mem_exclusive
contains a flag (0 or 1) that specifies whether other cpusets can share the memory nodes specified for this cpuset. By default (0), memory nodes are not allocated exclusively to one cpuset. Reserving memory nodes for the exclusive use of a cpuset (1) is functionally the same as enabling a memory hardwall with the `cpuset.mem_hardwall` parameter.

cpuset.mem_hardwall
contains a flag (0 or 1) that specifies whether kernel allocations of memory page and buffer data should be restricted to the memory nodes specified for this cpuset. By default (0), page and buffer data is shared across processes belonging to multiple users. With a hardwall enabled (1), each tasks’ user allocation can be kept separate.

cpuset.memory_pressure
a read-only file that contains a running average of the memory pressure created by the processes in this cpuset. The value in this pseudofile is automatically updated when `cpuset.memory_pressure_enabled` is enabled, otherwise, the pseudofile contains the value 0.

cpuset.memory_pressure_enabled
contains a flag (0 or 1) that specifies whether the system should compute the memory pressure created by the processes in this cgroup. Computed values are output to `cpuset.memory_pressure` and represent the rate at which processes attempt to free in-use memory, reported as an integer value of attempts to reclaim memory per second, multiplied by 1000.
cpuset.memory_spread_page
contains a flag (0 or 1) that specifies whether file system buffers should be spread evenly across
the memory nodes allocated to this cpuset. By default (0), no attempt is made to spread memory
pages for these buffers evenly, and buffers are placed on the same node on which the process
that created them is running.

cpuset.memory_spread_slab
contains a flag (0 or 1) that specifies whether kernel slab caches for file input/output operations
should be spread evenly across the cpuset. By default (0), no attempt is made to spread kernel
slab caches evenly, and slab caches are placed on the same node on which the process that
created them is running.

cpuset.sched_load_balance
contains a flag (0 or 1) that specifies whether the kernel will balance loads across the CPUs in this
cpuset. By default (1), the kernel balances loads by moving processes from overloaded CPUs to
less heavily used CPUs.

Note, however, that setting this flag in a cgroup has no effect if load balancing is enabled in
any parent cgroup, as load balancing is already being carried out at a higher level. Therefore,
to disable load balancing in a cgroup, disable load balancing also in each of its parents in the
hierarchy. In this case, you should also consider whether load balancing should be enabled for any
siblings of the cgroup in question.

cpuset.sched_relax_domain_level
contains an integer between -1 and a small positive value, which represents the width of
the range of CPUs across which the kernel should attempt to balance loads. This value is
meaningless if cpuset.sched_load_balance is disabled.

The precise effect of this value varies according to system architecture, but the following values
are typical:

<table>
<thead>
<tr>
<th>Value</th>
<th>Effect</th>
</tr>
</thead>
<tbody>
<tr>
<td>-1</td>
<td>Use the system default value for load balancing</td>
</tr>
<tr>
<td>0</td>
<td>Do not perform immediate load balancing; balance loads only periodically</td>
</tr>
<tr>
<td>1</td>
<td>Immediately balance loads across threads on the same core</td>
</tr>
<tr>
<td>2</td>
<td>Immediately balance loads across cores in the same package</td>
</tr>
<tr>
<td>3</td>
<td>Immediately balance loads across CPUs on the same node or blade</td>
</tr>
<tr>
<td>4</td>
<td>Immediately balance loads across several CPUs on architectures with non-uniform memory access (NUMA)</td>
</tr>
<tr>
<td>5</td>
<td>Immediately balance loads across all CPUs on architectures with NUMA</td>
</tr>
</tbody>
</table>

3.5. devices
The devices subsystem allows or denies access to devices by tasks in a cgroup.
The Device Whitelist (devices) subsystem is considered to be a Technology Preview in Red Hat Enterprise Linux 6.

Technology preview features are currently not supported under Red Hat Enterprise Linux 6 subscription services, might not be functionally complete, and are generally not suitable for production use. However, Red Hat includes these features in the operating system as a customer convenience and to provide the feature with wider exposure. You might find these features useful in a non-production environment and are also free to provide feedback and functionality suggestions for a technology preview feature before it becomes fully supported.

devices.allow

specifies devices to which tasks in a cgroup have access. Each entry has four fields: type, major, minor, and access. The values used in the type, major, and minor fields correspond to device types and node numbers specified in Linux Allocated Devices, otherwise known as the Linux Devices List and available from http://www.kernel.org/doc/Documentation/devices.txt.

type

type can have one of the following three values:

• a — applies to all devices, both character devices and block devices
• b — specifies a block device
• c — specifies a character device

major, minor

major and minor are device node numbers specified by Linux Allocated Devices. The major and minor numbers are separated by a colon. For example, 8 is the major number that specifies SCSI disk drives, and the minor number 1 specifies the first partition on the first SCSI disk drive; therefore 8:1 fully specifies this partition, corresponding to a file system location of /dev/sda1.

* can stand for all major or all minor device nodes, for example 9:* (all RAID devices) or *:* (all devices).

access

access is a sequence of one or more of the following letters:

• r — allows tasks to read from the specified device
• w — allows tasks to write to the specified device
• m — allows tasks to create device files that do not yet exist

For example, when access is specified as r, tasks can only read from the specified device, but when access is specified as rw, tasks can read from and write to the device.

devices.deny

specifies devices that tasks in a cgroup cannot access. The syntax of entries is identical with devices.allow.
devices.list

reports the devices for which access controls have been set for tasks in this cgroup.

### 3.6. freezer

The freezer subsystem suspends or resumes tasks in a cgroup.

**freezer.state**

freezer.state has three possible values:

- **FROZEN** — tasks in the cgroup are suspended.
- **FREEZING** — the system is in the process of suspending tasks in the cgroup.
- **THAWED** — tasks in the cgroup have resumed.

To suspend a specific process:

1. Move that process to a cgroup in a hierarchy which has the freezer subsystem attached to it.
2. Freeze that particular cgroup to suspend the process contained in it.

It is not possible to move a process into a suspended (frozen) cgroup.

Note that while the FROZEN and THAWED values can be written to freezer.state, FREEZING cannot be written, only read.

### 3.7. memory

The memory subsystem generates automatic reports on memory resources used by the tasks in a cgroup, and sets limits on memory use by those tasks:

**memory.stat**

reports a wide range of memory statistics, as described in the following table:

<table>
<thead>
<tr>
<th>Statistic</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>cache</td>
<td>page cache, including tmpfs (shmem), in bytes</td>
</tr>
<tr>
<td>rss</td>
<td>anonymous and swap cache, not including tmpfs (shmem), in bytes</td>
</tr>
<tr>
<td>mapped_file</td>
<td>size of memory-mapped mapped files, including tmpfs (shmem), in bytes</td>
</tr>
<tr>
<td>pgpgin</td>
<td>number of pages paged into memory</td>
</tr>
<tr>
<td>pgpgout</td>
<td>number of pages paged out of memory</td>
</tr>
<tr>
<td>swap</td>
<td>swap usage, in bytes</td>
</tr>
<tr>
<td>active_anon</td>
<td>anonymous and swap cache on active least-recently-used (LRU) list, including tmpfs (shmem), in bytes</td>
</tr>
<tr>
<td>inactive_anon</td>
<td>anonymous and swap cache on inactive LRU list, including tmpfs (shmem), in bytes</td>
</tr>
<tr>
<td>active_file</td>
<td>file-backed memory on active LRU list, in bytes</td>
</tr>
<tr>
<td>inactive_file</td>
<td>file-backed memory on inactive LRU list, in bytes</td>
</tr>
<tr>
<td>unevictable</td>
<td>memory that cannot be reclaimed, in bytes</td>
</tr>
</tbody>
</table>
### Chapter 3. Subsystems and Tunable Parameters

<table>
<thead>
<tr>
<th>Statistic</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>hierarchical_memory_limit</td>
<td>memory limit for the hierarchy that contains the memory cgroup, in bytes</td>
</tr>
<tr>
<td>hierarchical_memsw_limit</td>
<td>memory plus swap limit for the hierarchy that contains the memory cgroup, in bytes</td>
</tr>
</tbody>
</table>

Additionally, each of these files other than `hierarchical_memory_limit` and `hierarchical_memsw_limit` has a counterpart prefixed `total_` that reports not only on the cgroup, but on all its children as well. For example, `swap` reports the swap usage by a cgroup and `total_swap` reports the total swap usage by the cgroup and all its child groups.

When you interpret the values reported by `memory.stat`, note how the various statistics interrelate:

- $active\_anon + inactive\_anon = \text{anonymous memory + file cache for tmpfs + swap cache}$

  Therefore, $active\_anon + inactive\_anon \neq rss$, because $rss$ does not include tmpfs.

- $active\_file + inactive\_file = \text{cache - size of tmpfs}$

`memory.usage\_in\_bytes`

- reports the total current memory usage by processes in the cgroup (in bytes).

`memory.memsw.usage\_in\_bytes`

- reports the sum of current memory usage plus swap space used by processes in the cgroup (in bytes).

`memory.max\_usage\_in\_bytes`

- reports the maximum memory used by processes in the cgroup (in bytes).

`memory.memsw.max\_usage\_in\_bytes`

- reports the maximum amount of memory and swap space used by processes in the cgroup (in bytes).

`memory.limit\_in\_bytes`

- sets the maximum amount of user memory (including file cache). If no units are specified, the value is interpreted as bytes. However, it is possible to use suffixes to represent larger units — k or K for kilobytes, m or M for Megabytes, and g or G for Gigabytes.

  You cannot use `memory.limit\_in\_bytes` to limit the root cgroup; you can only apply values to groups lower in the hierarchy.

  Write `-1` to `memory.limit\_in\_bytes` to remove any existing limits.

`memory.memsw.limit\_in\_bytes`

- sets the maximum amount for the sum of memory and swap usage. If no units are specified, the value is interpreted as bytes. However, it is possible to use suffixes to represent larger units — k or K for kilobytes, m or M for Megabytes, and g or G for Gigabytes.

  You cannot use `memory.memsw.limit\_in\_bytes` to limit the root cgroup; you can only apply values to groups lower in the hierarchy.

  Write `-1` to `memory.memsw.limit\_in\_bytes` to remove any existing limits.
It is important to set the `memory.limit_in_bytes` parameter *before* setting the `memory.memsw.limit_in_bytes` parameter; attempting to do so in the reverse order results in an error. This is because `memory.memsw.limit_in_bytes` becomes available only after all memory limitations (previously set in `memory.limit_in_bytes`) are exhausted.

Consider the following example: setting `memory.limit_in_bytes = 2G` and `memory.memsw.limit_in_bytes = 4G` for a certain cgroup will allow processes in that cgroup to allocate 2 GB of memory and, once exhausted, allocate another 2 GB of swap only; the `memory.memsw.limit_in_bytes` parameter represents a sum of memory and swap. Processes in a cgroup that does not have the `memory.memsw.limit_in_bytes` parameter set can potentially use up all the available swap (after exhausting the set memory limitation) and trigger an Out Of Memory situation caused by the lack of available swap.

The order in which the `memory.limit_in_bytes` and `memory.memsw.limit_in_bytes` parameters are set in the `/etc/cgconfig.conf` file is important as well. The following is a correct example of such a configuration:

```
memory {  
    memory.limit_in_bytes = 1G;
    memory.memsw.limit_in_bytes = 1G;
}
```

memory.failcnt reports the number of times that the memory limit has reached the value set in `memory.limit_in_bytes`.

memory.memsw.failcnt reports the number of times that the memory plus swap space limit has reached the value set in `memory.memsw.limit_in_bytes`.

memory.force_empty
when set to 0, empties memory of all pages used by tasks in this cgroup. This interface can only be used when the cgroup has no tasks. If memory cannot be freed, it is moved to a parent cgroup if possible. Use the memory.force_empty parameter before removing a cgroup to avoid moving out-of-use page caches to its parent cgroup.

memory.swappiness sets the tendency of the kernel to swap out process memory used by tasks in this cgroup instead of reclaiming pages from the page cache. This is the same tendency, calculated the same way, as set in `/proc/sys/vm/swappiness` for the system as a whole. The default value is 60. Values lower than 60 decrease the kernel's tendency to swap out process memory, values greater than 60 increase the kernel's tendency to swap out process memory, and values greater than 100 permit the kernel to swap out pages that are part of the address space of the processes in this cgroup.
Note that a value of 0 does not prevent process memory being swapped out; swap out might still happen when there is a shortage of system memory because the global virtual memory management logic does not read the cgroup value. To lock pages completely, use mlock() instead of cgroups.

You cannot change the swappiness of the following groups:

- the root cgroup, which uses the swappiness set in /proc/sys/vm/swappiness.
- a cgroup that has child groups below it.

memory.use_hierarchy contains a flag (0 or 1) that specifies whether memory usage should be accounted for throughout a hierarchy of cgroups. If enabled (1), the memory subsystem reclaims memory from the children of and process that exceeds its memory limit. By default (0), the subsystem does not reclaim memory from a task's children.

3.8. net_cls

The net_cls subsystem tags network packets with a class identifier (classid) that allows the Linux traffic controller (tc) to identify packets originating from a particular cgroup. The traffic controller can be configured to assign different priorities to packets from different cgroups.

net_cls.classid

net_cls.classid contains a single value that indicates a traffic control handle. The value of classid read from the net_cls.classid file is presented in the decimal format while the value to be written to the file is expected in the hexadecimal format. For example, 0x100001 represents the handle conventionally written as 10:1 in the format used by iproute2. In the net_cls.classid file, it would be represented by the number 1048577.

The format for these handles is: 0xAAAAABBBS, where AAAA is the major number in hexadecimal and BBBB is the minor number in hexadecimal. You can omit any leading zeroes; 0x10001 is the same as 0x00010001, and represents 1:1. The following is an example of setting a 10:1 handle in the net_cls.classid file:

```
~# echo 0x100001 > /cgroup/net_cls/red/net_cls.classid
~# cat /cgroup/net_cls/red/net_cls.classid
1048577
```

Refer to the man page for tc to learn how to configure the traffic controller to use the handles that the net_cls adds to network packets.

3.9. ns

The ns subsystem provides a way to group processes into separate namespaces. Within a particular namespace, processes can interact with each other but are isolated from processes running in other namespaces. These separate namespaces are sometimes referred to as containers when used for operating-system-level virtualization.
3.10. Additional Resources

Subsystem-Specific Kernel Documentation
All of the following files are located under the /usr/share/doc/kernel-doc-<kernel_version>/Documentation/cgroups/ directory (provided by the kernel-doc package).

- blkio subsystem — blkio-controller.txt
- cpucct subsystem — cpuacct.txt
- cpuset subsystem — cpusets.txt
- devices subsystem — devices.txt
- freezer subsystem — freezer-subsystem.txt
- memory subsystem — memory.txt
Appendix A. Revision History

Revision 1.0-6  Tue Dec 6 2011  Martin Prpič mprpic@redhat.com

Revision 1.0-5  Thu May 19 2011  Martin Prpič mprpic@redhat.com

Revision 1.0-4  Tue Mar 1 2011  Martin Prpič mprpic@redhat.com
Fixed multiple examples — BZ#667623\(^1\), BZ#667676\(^2\), BZ#667699\(^3\)
Clarification of the cgclear command — BZ#577101\(^4\)
Clarification of the lssubsystem command — BZ#678517\(^5\)
Freezing a process — BZ#677548\(^6\)

Revision 1.0-3  Wed Nov 17 2010  Rüdiger Landmann
r.landmann@redhat.com
Correct remount example — BZ#612805\(^7\)

Revision 1.0-2  Thu Nov 11 2010  Rüdiger Landmann
r.landmann@redhat.com
Remove pre-release feedback instructions

Revision 1.0-1  Wed Nov 10 2010  Rüdiger Landmann
r.landmann@redhat.com
Corrections from QE — BZ#581702\(^8\) and BZ#612805\(^9\)

Revision 1.0-0  Tue Nov 9 2010  Rüdiger Landmann
r.landmann@redhat.com
Feature-complete version for GA